5. Заключение

В работе получено решение задачи поиска динамического регулятора для стационарной системы с мультипликативными шумами. При выводе достаточных условий ограниченности анизотропийной нормы замкнутой системы была использована взаимно однозначная замена линеаризующая замена переменных, позволяющая свести поиск матриц регулятора в пространстве состояний к решению задачи выпуклой оптимизации.

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